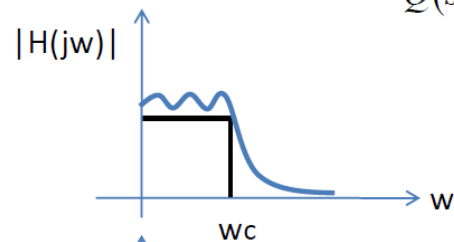


FILTROS ACTIVOS COMO APLICACIÓN LINEAL

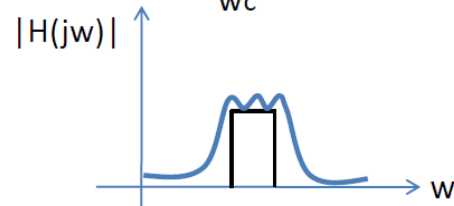
- Circuitos de primer orden:
- Circuitos de segundo orden:
Sallen-Key

Un filtro es un sistema lineal que elimina partes del espectro

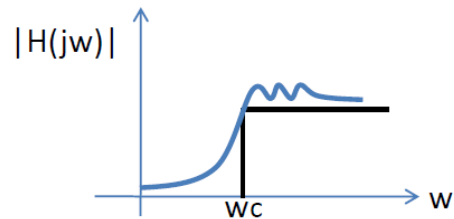
$$H(s) = \frac{P(s)}{Q(s)} = \frac{s^M a_{M-1} s^{M-1} \dots a_1 s + a_0}{s^N + b_{N-1} s^{N-1} \dots b_1 s + b_0}$$



Filtro ideal/real paso bajo



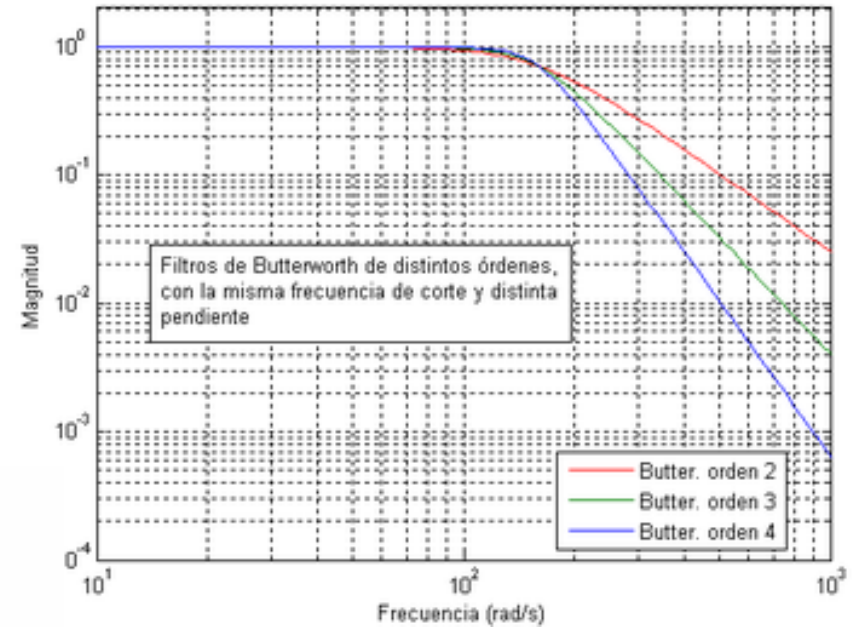
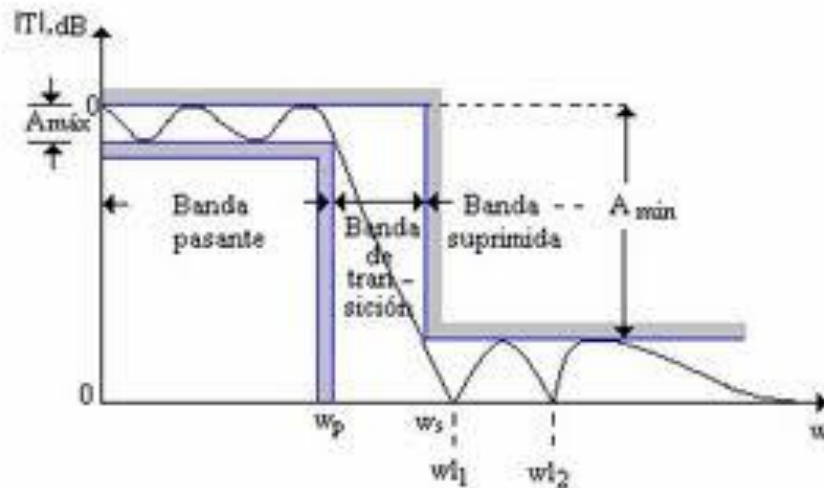
Filtro ideal/real paso banda



Filtro ideal/real paso alto

Teoría de aproximación de filtros

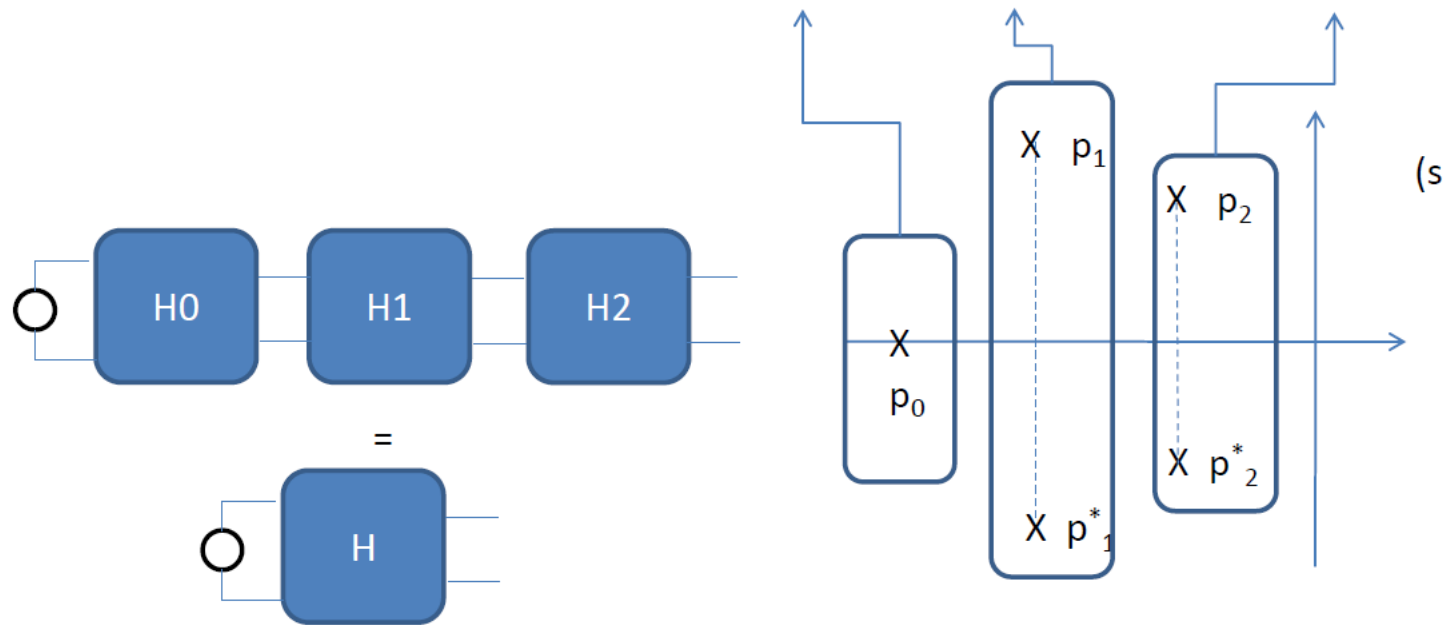
$$|H(\Omega)|^2 = \frac{1}{1 + (\Omega/\Omega_c)^{2N}}$$



- Aproximación de magnitud pasa baja
- Aproximación maximalmente plana
- Butterworth
- Chebyshev inversa
- Aproximación de igual rizado
- Chebyshev
- Elíptica
- Aproximación Bessel

Síntesis de filtros en cascada

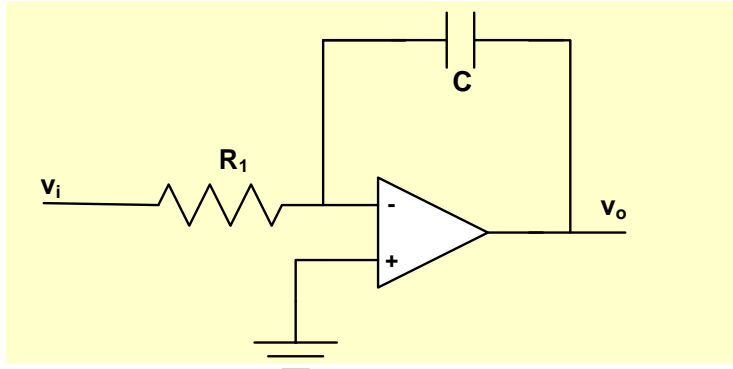
$$H(s) = \frac{P(s)}{Q(s)} = \frac{K}{s^N + b_{N-1}s^{N-1} \dots b_1s + b_0} = \frac{k_0}{s + p_0} \cdot \frac{k_1}{(s - p_1) \cdot (s - p_1^*)} \cdot \frac{k_2}{(s - p_2) \cdot (s - p_2^*)} \dots$$



•Circuitos de primer orden

IDEAL

Integrador



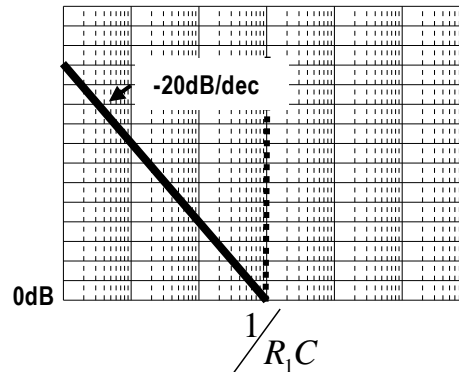
$$\frac{V_o}{V_i}(s) = -\frac{1}{sR_1C} \quad \bullet \text{ Polo } s = 0$$

$$\frac{V_o}{V_i}(j\omega) = -\frac{1}{j\omega R_1C}$$

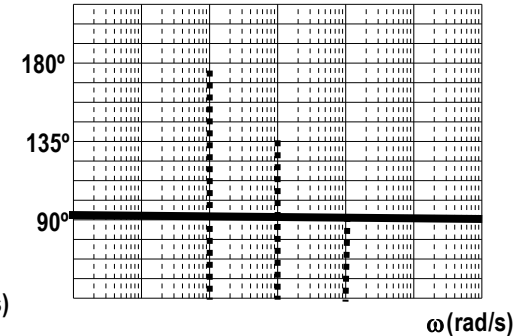
- Cortocircuito virtual: $v_+ = v_-$
- $i(R_1) = i(C)$

$$v_o(t) = -\frac{1}{R_1C} \int v_i(t) + v_o(0)$$

$|v_o/v_i(j\omega)|(\text{dB})$



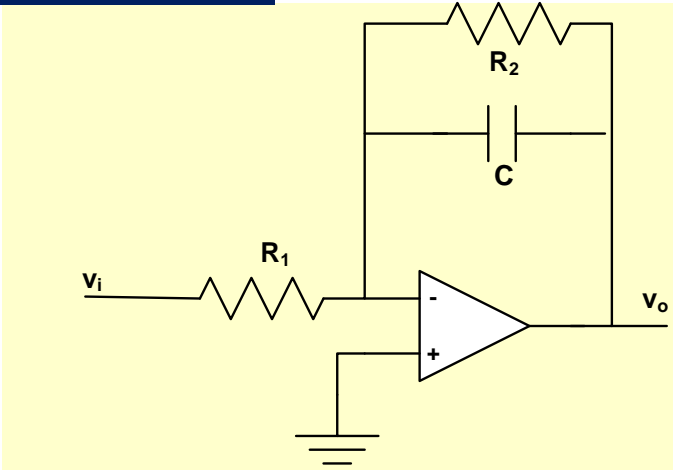
$\angle v_o/v_i(j\omega)(^\circ)$



- Integra $\forall \omega$

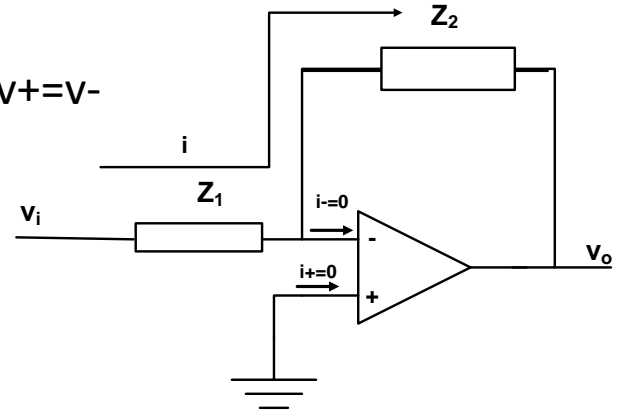
$$\bullet \left. \frac{v_o}{v_i} \right|_{DC} \rightarrow \infty$$

REAL



Integrador

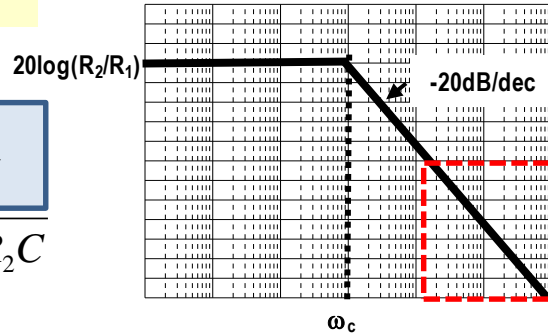
- Cortocircuito virtual: $v_+ = v_-$
- $i(Z_1) = i(Z_2) = i$



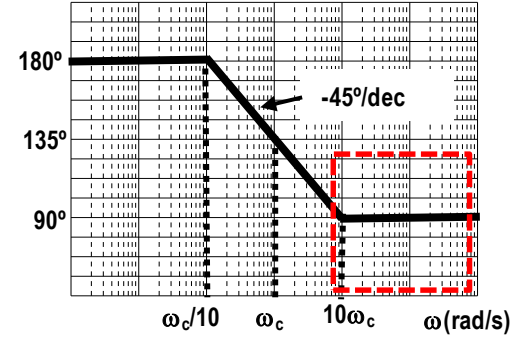
$$\frac{V_o}{V_i}(j\omega) = -\frac{Z_2}{Z_1} = -\frac{R_2}{R_1} \frac{1}{1 + j\omega R_2 C} = -\frac{R_2}{R_1} \frac{1}{1 + j\omega R_2 C}$$

Polo: $\omega_c = \frac{1}{R_2 C}$

$|v_o/v_i(j\omega)|$ (dB)

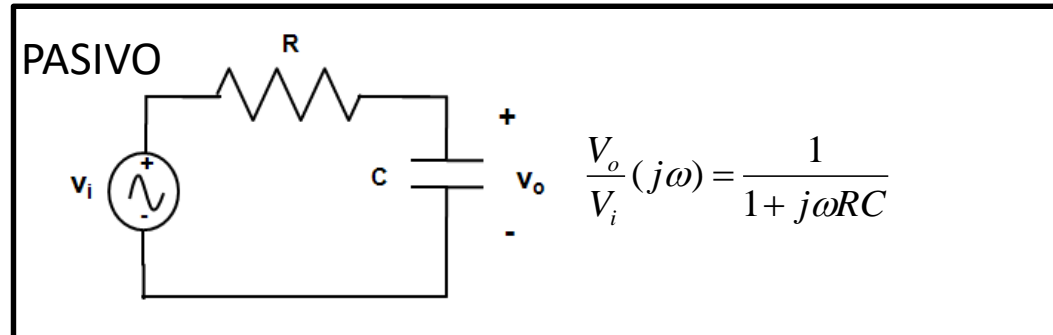


$\angle v_o/v_i(j\omega)$ (°)



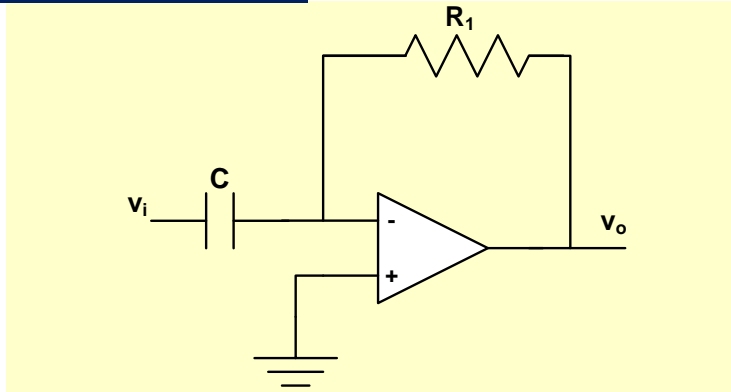
Integra si $\omega \gg 1/R_2 C$

$$\left. \frac{v_o}{v_i} \right|_{BF} \rightarrow -\frac{R_1}{R_2}$$



IDEAL

Derivador

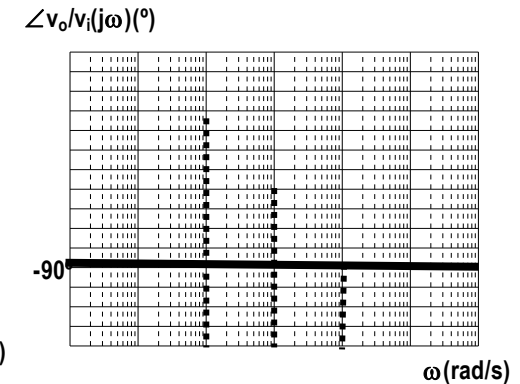
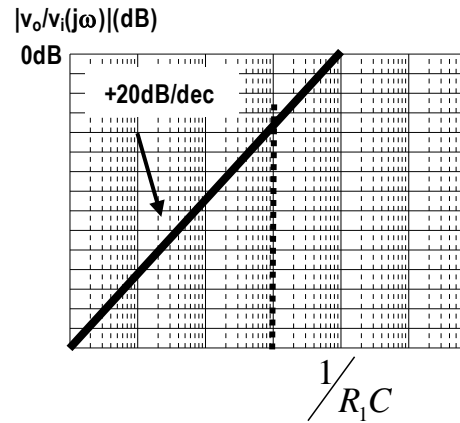


- Cortocircuito virtual: $v_+ = v_-$
- $i(R_1) = i(C)$

$$v_o(t) = -R_1 C \cdot \frac{dv_i(t)}{dt}$$

$$\frac{V_o}{V_i}(s) = -sR_1C \quad \bullet \text{ Polo } s \rightarrow \infty$$

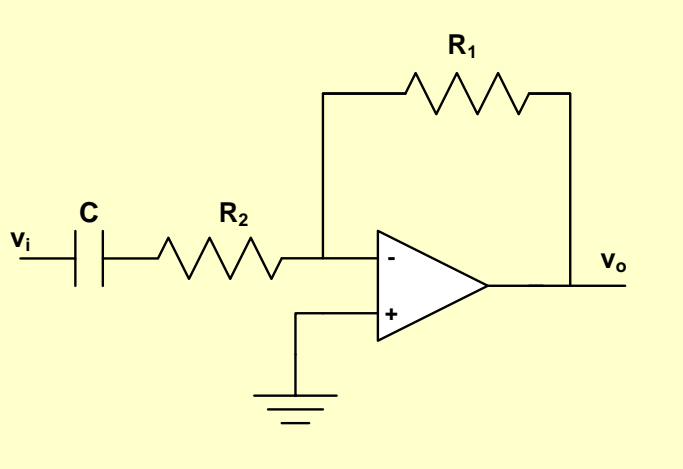
$$\frac{V_o}{V_i}(j\omega) = -j\omega R_1C$$



- Deriva $\forall \omega$

$$\bullet \left. \frac{V_o}{V_i} \right|_{HF} \rightarrow \infty$$

REAL

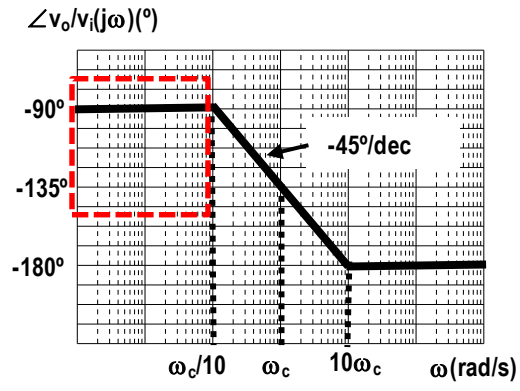
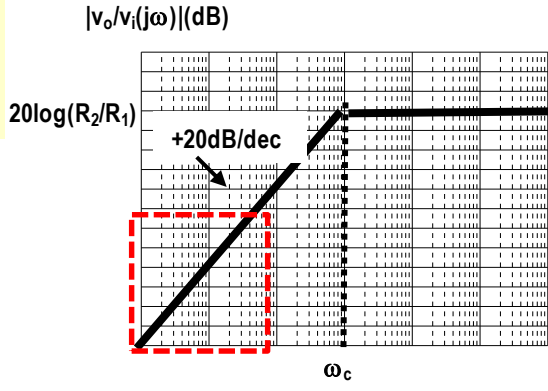
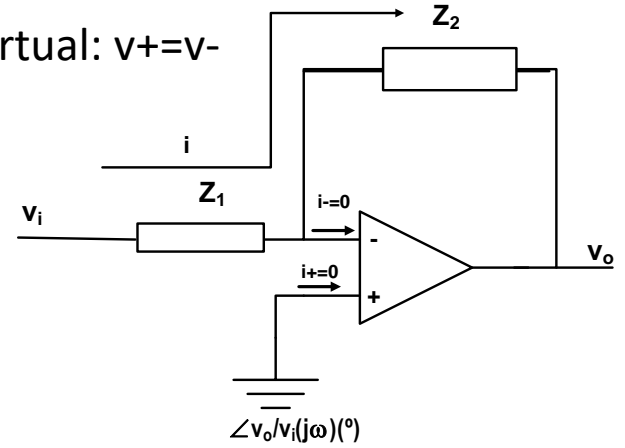


$$\frac{V_o}{V_i}(j\omega) = -\frac{Z_2}{Z_1} = \frac{-j\omega \cdot R_1 \cdot C}{1 + j\omega R_2 C}$$

Polo: $\omega_c = \frac{1}{R_2 C}$

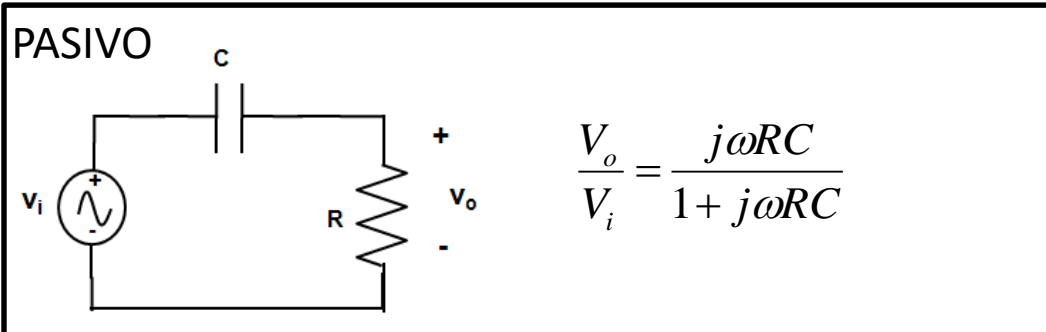
Derivador

- Cortocircuito virtual: $v_+ = v_-$
- $i(Z_1) = i(Z_2) = i$



Deriva si $\omega \ll 1/R_2 C$

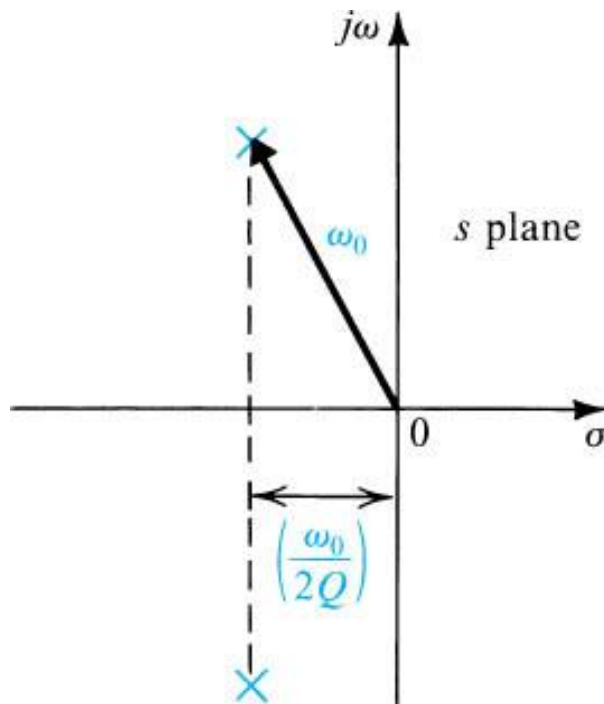
$$\left. \frac{V_o}{V_i} \right|_{HF} \rightarrow -\frac{R_1}{R_2}$$



Filter Type and $T(s)$	s-Plane Singularities	Bode Plot for $ T $	Passive Realization	Op Amp-RC Realization
(a) Low pass (LP) $T(s) = \frac{a_0}{s + \omega_0}$			<p> $CR = \frac{1}{\omega_0}$ DC gain = 1 </p>	<p> $CR_2 = \frac{1}{\omega_0}$ DC gain = $-\frac{R_2}{R_1}$ </p>
(b) High pass (HP) $T(s) = \frac{a_1 s}{s + \omega_0}$			<p> $CR = \frac{1}{\omega_0}$ High-frequency gain = 1 </p>	<p> $CR_1 = \frac{1}{\omega_0}$ High-frequency gain = $-\frac{R_2}{R_1}$ </p>
(c) General $T(s) = \frac{a_1 s + a_0}{s + \omega_0}$			<p> $(C_1 + C_2)(R_1 // R_2) = \frac{1}{\omega_0}$ $C_1 R_1 = \frac{a_1}{a_0}$ DC gain = $\frac{R_2}{R_1 + R_2}$ HF gain = $\frac{C_1}{C_1 + C_2}$ </p>	<p> $C_2 R_2 = \frac{1}{\omega_0}$ $C_1 R_1 = \frac{a_1}{a_0}$ DC gain = $-\frac{R_2}{R_1}$ HF gain = $-\frac{C_1}{C_2}$ </p>

- Circuitos de segundo orden:
Sallen-Key

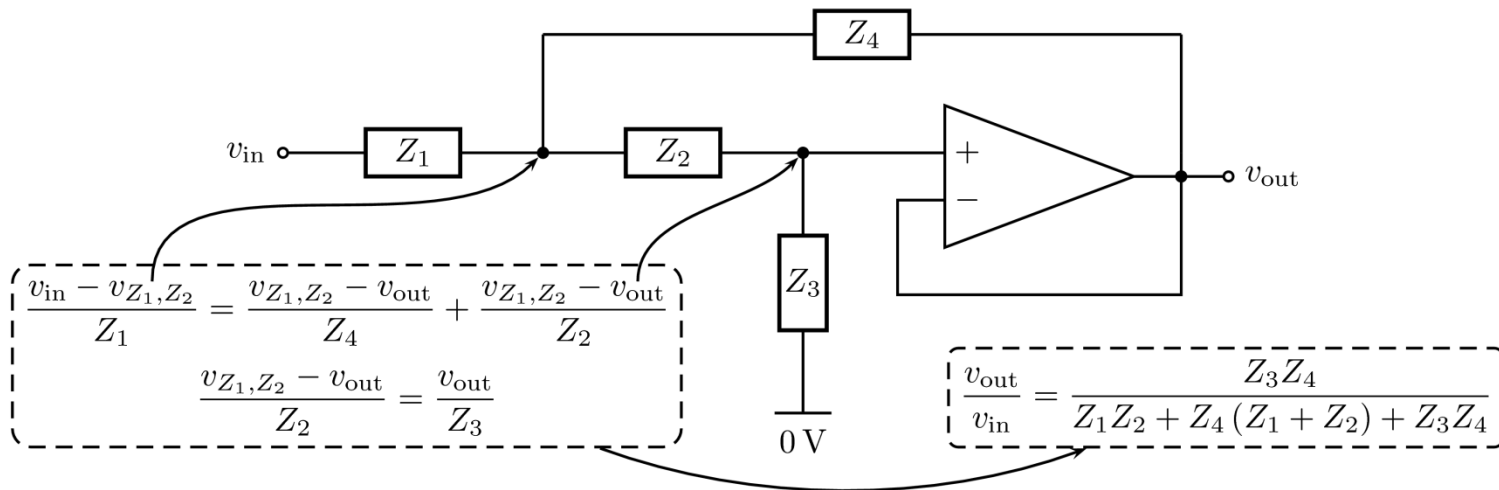
$$H(s) = \frac{P(s)}{Q(s)} = \frac{A_2s^2 + A_1s + A_0}{s^2 + \frac{\omega_o}{Q}s + \omega_o^2} = \frac{A_2s^2 + A_1s + A_0}{(s - p_1) \cdot (s - p_1^*)}$$



A_2, A_1, A_0 determinan el tipo de filtro

Filter Type and $T(s)$	s -Plane Singularities	$ T $
<p>(a) Low pass (LP)</p> $T(s) = \frac{a_0}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2}$ <p>DC gain = $\frac{a_0}{\omega_0^2}$</p>		
<p>(b) High pass (HP)</p> $T(s) = \frac{a_2 s^2}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2}$ <p>High-frequency gain = a_2</p>		
<p>(c) Bandpass (BP)</p> $T(s) = \frac{a_1 s}{s^2 + s\frac{\omega_0}{Q} + \omega_0^2}$ <p>Center-frequency gain = $\frac{a_1 Q}{\omega_0}$</p>		

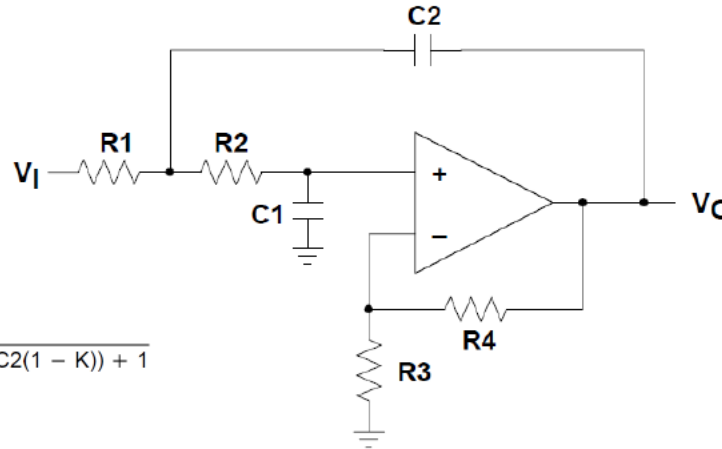
Sallen-Key



<http://focus.ti.com.cn/cn/lit/an/sloa024b/sloa024b.pdf>

Sallen Key paso bajo

Filtro de Sallen-Key



$$\frac{V_o}{V_i}(lp) = \frac{K}{s^2(R1R2C1C2) + s(R1C1 + R2C1 + R1C2(1 - K)) + 1}$$

Figure 5. Low-Pass Sallen-Key Circuit

$$f_c = \frac{1}{2\pi\sqrt{R1R2C1C2}}, \text{ and } Q = \frac{\sqrt{R1R2C1C2}}{R1C1 + R2C1 + R1C2(1 - K)}$$

Sallen Key paso bajo de ganancia intensificada

Si $R1=R2=R$, $C=C1=C2$

$$f_c = \frac{1}{2\pi RC} \quad Q = \frac{1}{3 - K}$$