

# Introduction to Embedded System

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Universidad  
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Departamento  
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# Future of IT?

□ According to forecasts characterized by the terms such as

- *Post-PC era*
- *Disappearing computer*
- *Ubiquitous computing*
- *Pervasive computing*
- *Ambient intelligence*
- *Embedded systems*



# What is an embedded systems?



iPhone



Laser Keyboard



Nikon D300



Video Watch



GPS



Playstation 3



PC Keyboard



SD Card

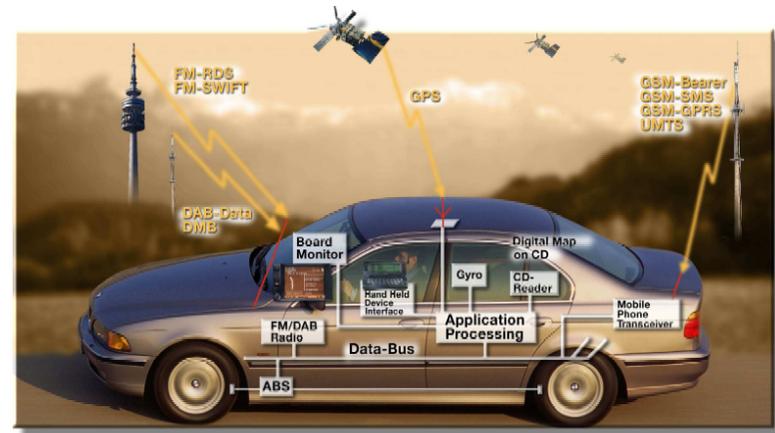
**Embedded systems (ES) = information processing systems embedded into a larger product**

# What is an embedded system?



Avionics

Communication



Automobile



Consumer Electronics

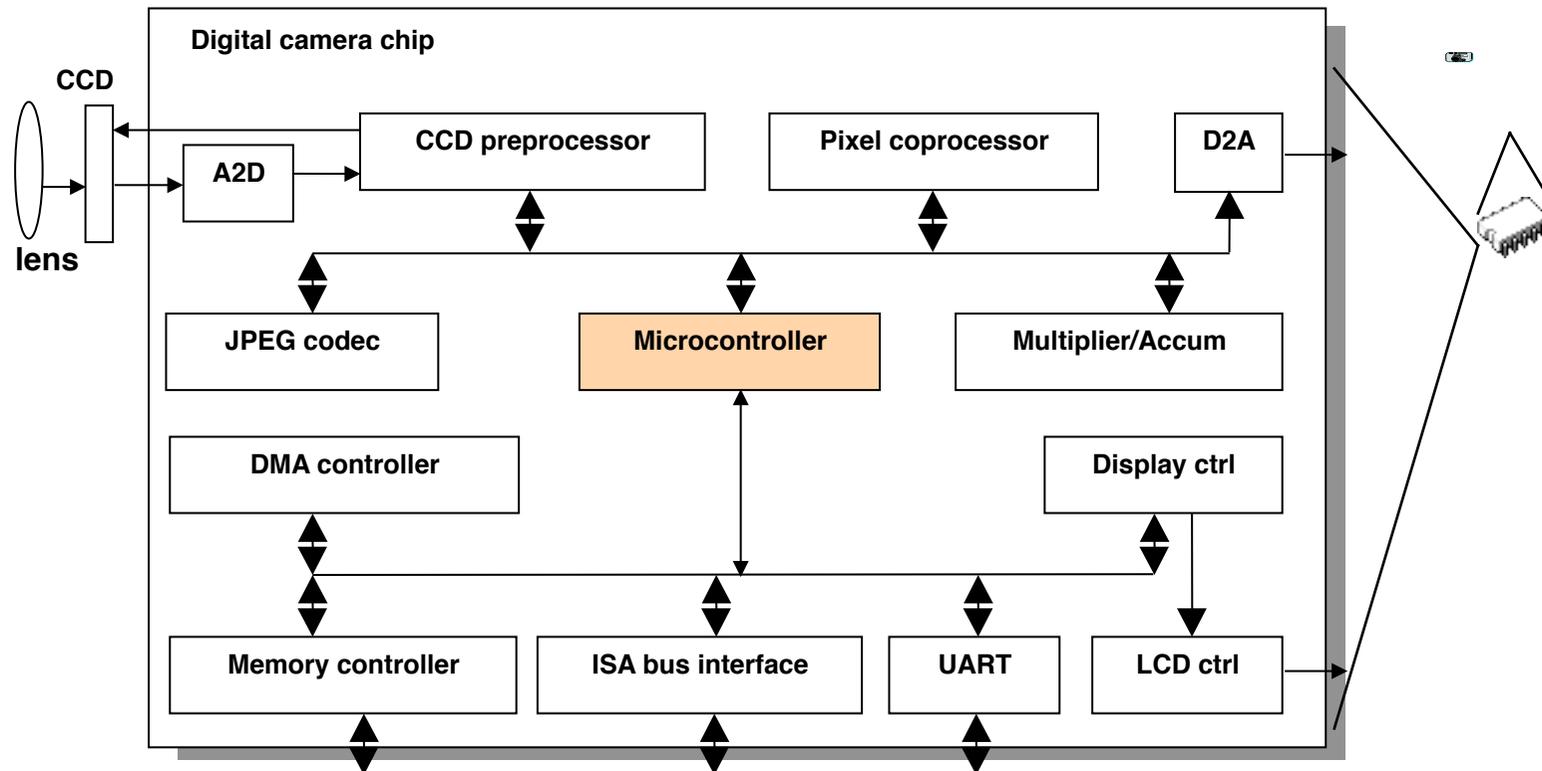


Office Equipments

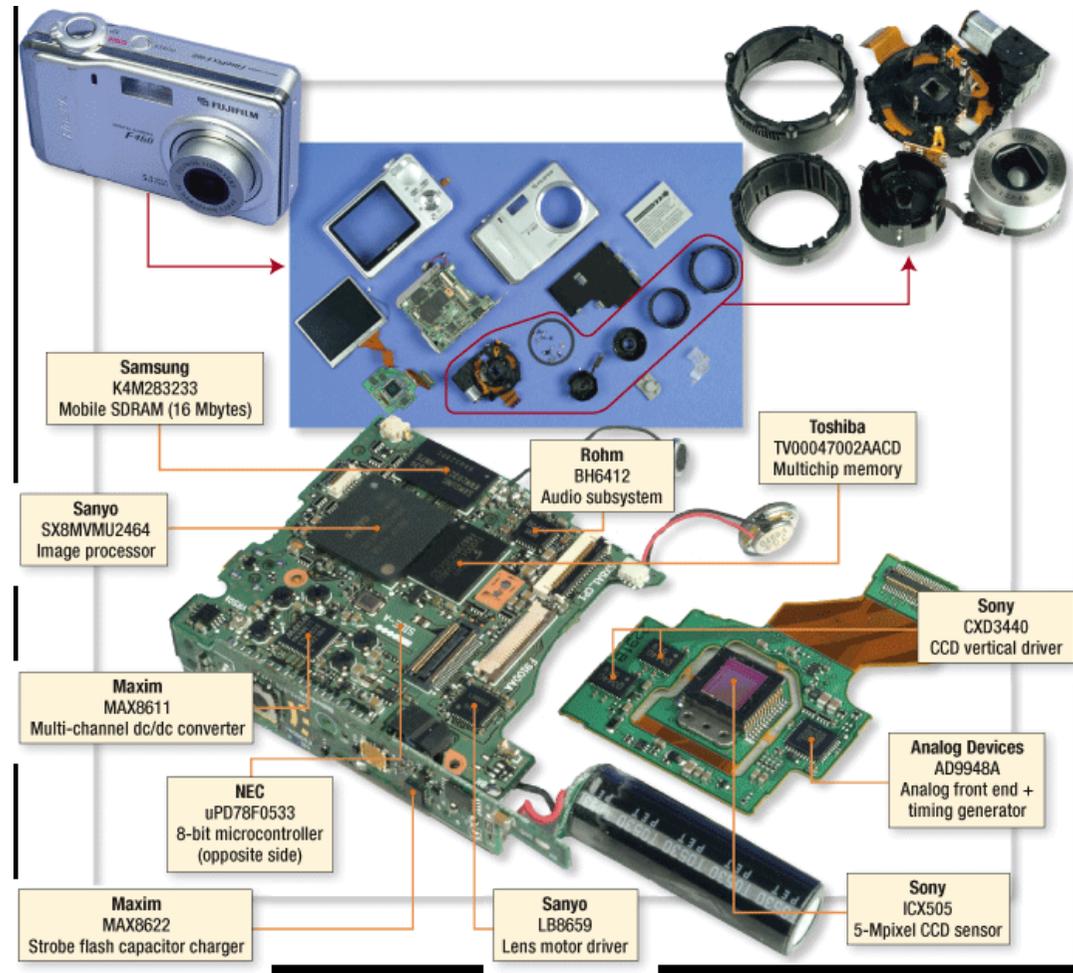


Household Appliances

## An embedded system example -- a digital camera



# An embedded system example -- a digital camera



# Application areas

1. Automotive electronics



2. Aircraft electronics



3. Trains



4. Telecommunication



# Application areas

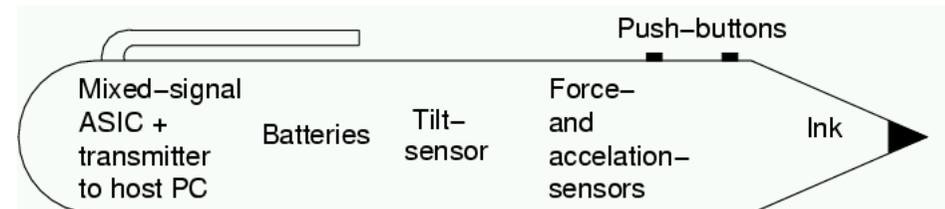
5. Medical systems  
e.g. “artificial eye”



6. Military applications

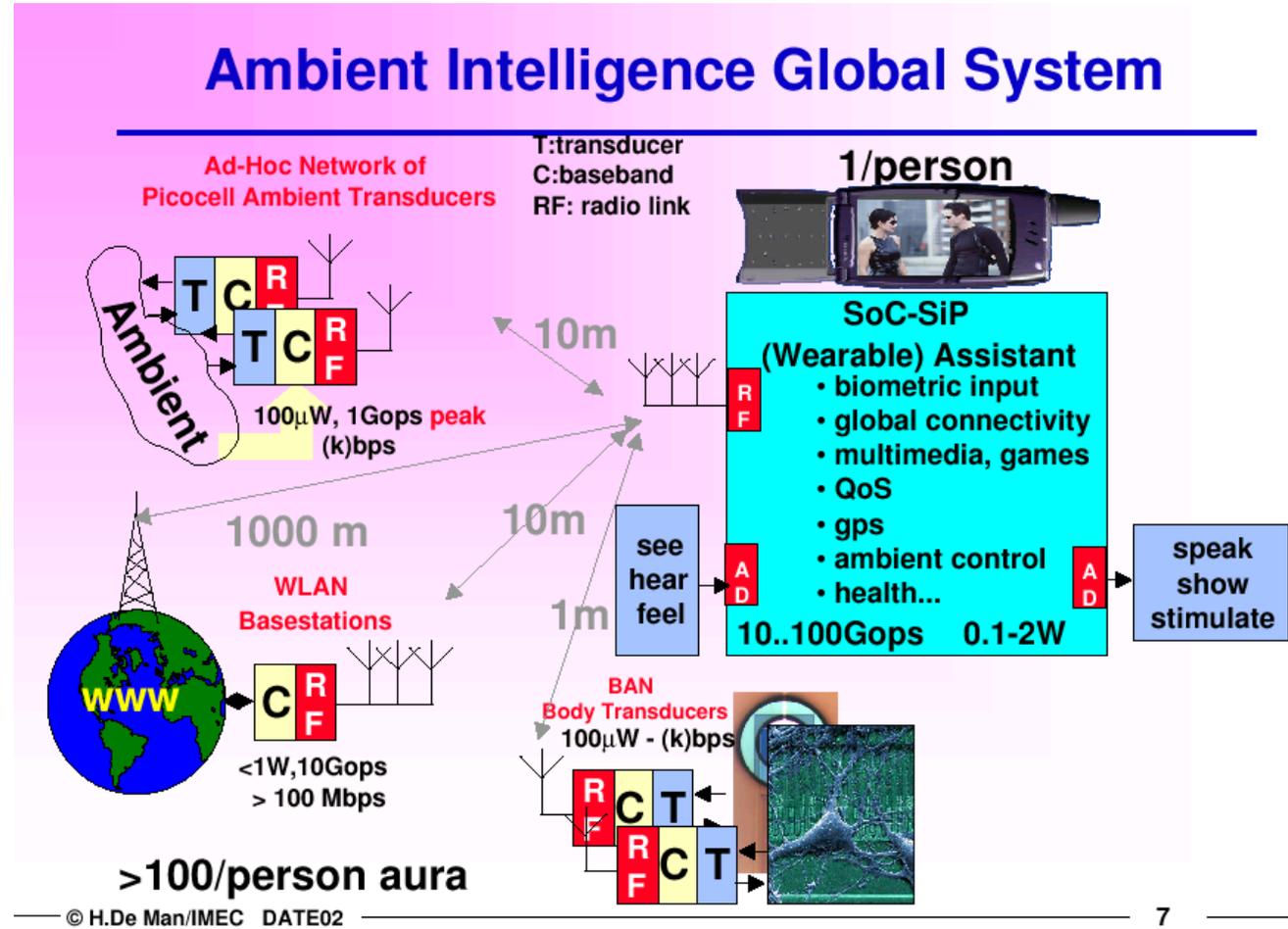


7. Authentication



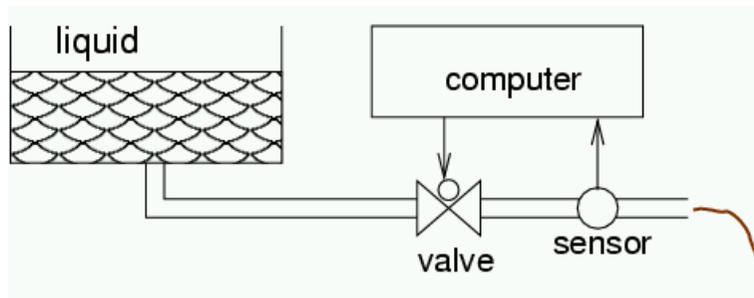
# Application areas

## 8. Consumer electronics



# Application areas

## 9. Fabrication equipment



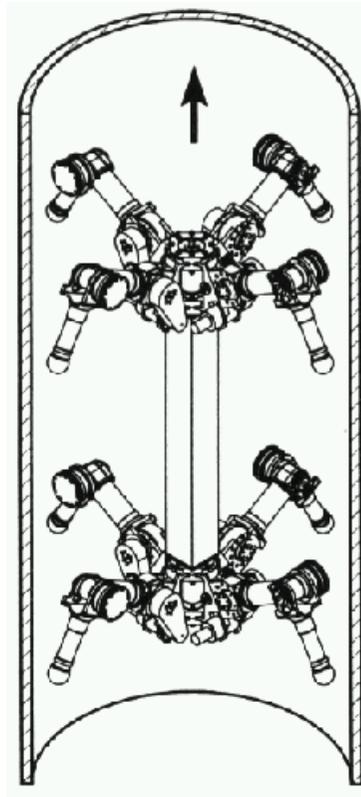
## 10. Smart buildings



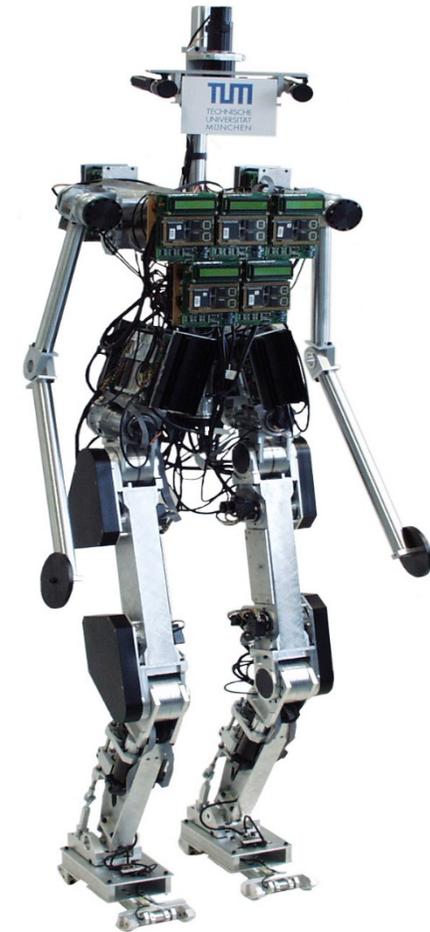
# Application areas

## 11. Robotics

„Pipe-climber“



Robot  
„Johnnie“ (C  
ourtesy and  
©: H. Ulbrich,  
F. Pfeiffer,  
TU  
München)



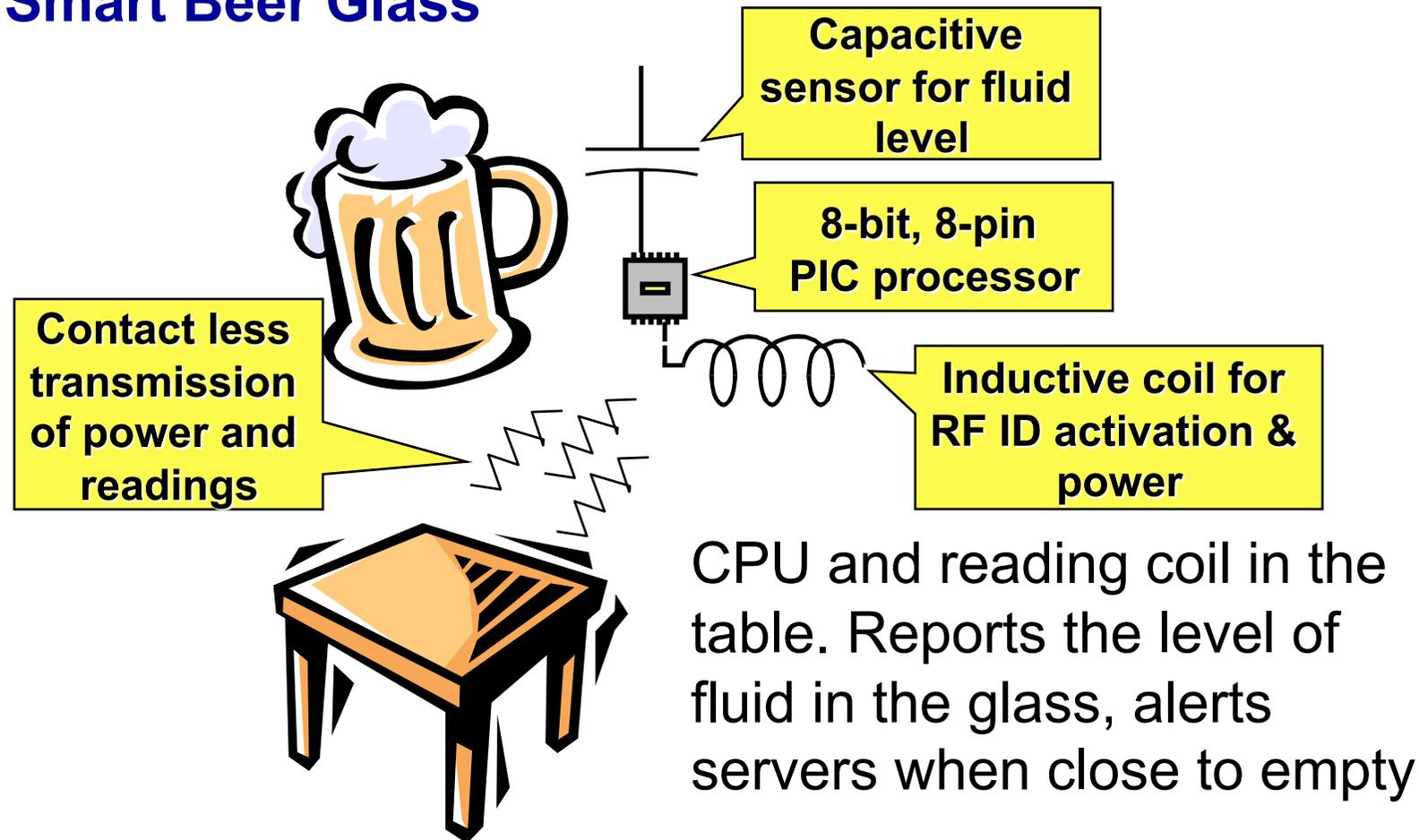
## Embedded systems from real life

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- Typical embedded solution
- Integrates several technologies:
  - Radio transmissions
  - Sensor technology
  - Magnetic inductance for power
  - Computer used for calibration
- Impossible without the computer
- Meaningless without the electronics

## Embedded systems from real life

### Smart Beer Glass



# Embedded systems from real life

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## Mobile Phones and Base Stations



Multiprocessor

8-bit/32-bit for UI; DSP for signals

32-bit in IR port; 32-bit in Bluetooth

8-100 MB of memory

All custom chips



Massive signal processing

Several processing tasks per connected call

Based on DSPs

Standard or custom

100s of processors

## Embedded systems from real life



# Embedded systems from real life

**SST**  
**SST25VF080B**  
1 MB Serial Flash

**SAMSUNG**  
Application Processor and DDR SDRAM

**ST MICROELECTRONICS**  
**LIS331 DL**  
Accelerometer

**INFINEON**  
**SMP3i**  
SMARTi Power Management IC

**SKYWORKS**  
**SKY77340**  
Power Amp. Module

**INFINEON**  
UMTS Transceiver

**NATIONAL SEMICONDUCTOR**  
**LM2512AA**  
Display Interface

**TRIQUINT**  
**TQM666032**  
WCDMA/HSUPA Power Amp.

**BROADCOM**  
**BCM5974**  
Touchscreen Controller

**TRIQUINT**  
**TQM676031**  
WCDMA/HSUPA Power Amp.

**WOLFSON**  
**WM6180C**  
Audio Codec

**TRIQUINT**  
**TQM616035**  
WCDMA/HSUPA Power Amp.

**INFINEON**  
**PMB2525**  
Hammerhead II GPS

**LINEAR TECHNOLOGY**  
**LTC4088-2**  
Battery Charger/ USB Controller

**NXP**  
Power Management

**NUMONYX**  
**PF38F3050M0Y0CE**  
16 MB NOR + 8 MB Pseudo - SRAM

**INFINEON**  
Digital Baseband Processor

**Semiconductor insights<sup>inc.</sup>**

# Embedded systems from real life

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## Cars

Multiple processors  
Up to 100  
Networked together

Multiple networks  
Body, engine, telematics, media,  
safety

Large diversity in processor types:  
8-bit – door locks, lights, etc.  
16-bit – most functions  
32-bit – engine control, airbags

Functions by embedded processing:  
ABS: Anti-lock braking systems  
ESP: Electronic stability control  
Airbags  
Efficient automatic gearboxes  
Theft prevention with smart keys  
Blind-angle alert systems  
... etc ...



# Embedded systems from real life

## Extremely Large

Functions requiring computers:

Radar

Weapons

Damage control

Navigation

basically everything

Computers:

Large servers

1000s of processors



# Embedded systems from real life

## Inside Your PC

Custom processors  
Graphics, sound  
32-bit processors  
IR, Bluetooth  
Network, WLAN  
Harddisk  
RAID controllers  
8-bit processors  
USB  
Keyboard, mouse

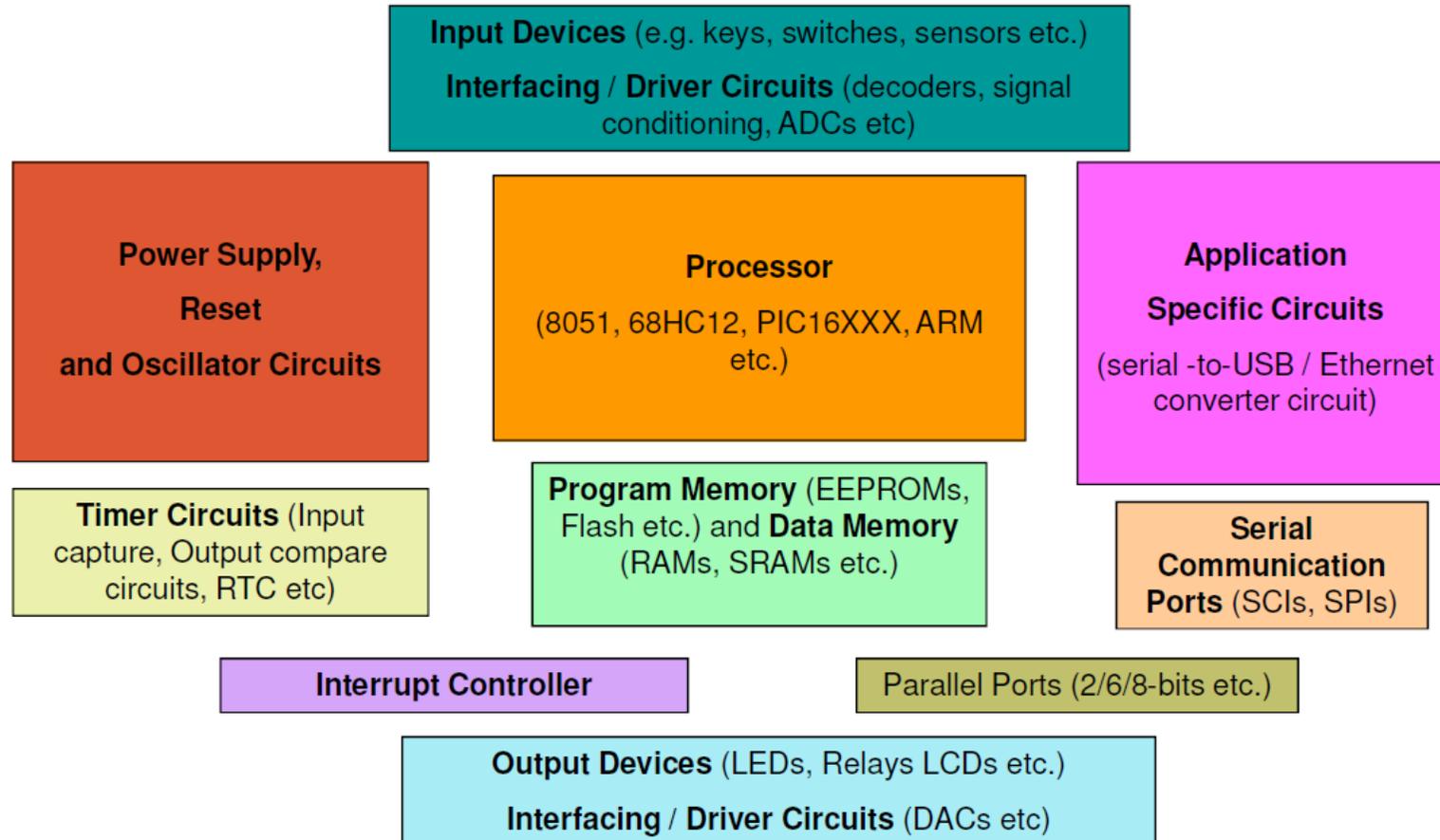


# Components of Embedded Systems

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- ❑ Analog Components
  - ✓ Sensors, Actuators, Controllers, ...
- ❑ Digital Components
  - ✓ Processor, Coprocessors
  - ✓ Memories
  - ✓ Controllers, Buses
  - ✓ Application Specific Integrated Circuits (ASIC)
- ❑ Converters – A2D, D2A, ...
- ❑ Software
  - ✓ Application Programs
  - ✓ Exception Handlers

# Components of Embedded Systems



# Components of Embedded Systems

## Input Devices

Switches



Keypads



Sensors



# Components of Embedded Systems

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## Processors



# Components of Embedded Systems

## ❑ 1) Main application software:

- ✓ performs series of tasks or multiple tasks concurrently.
- ✓ constrained due to low memory, low processing power requirement etc.

## ❑ 2. Real Time Operating System (RTOS):

- ✓ supervises the application software.
- ✓ provides a mechanism to let the processor run a process as per scheduling.
- ✓ performs context-switching between various processes (tasks).
- ✓ organizes access to a resource in sequence of the series of tasks of the system.
- ✓ schedules their working and execution by following a plan to control the latencies and to meet the deadlines.
- ✓ sets the rules during the execution of the application software.

# Growing importance of embedded systems



- Growing economical importance of embedded systems: [www.itfacts.biz]
  - *Worldwide mobile phone sales surpassed 156.4 mln units in Q2 2004, a 35% increase from Q2 2003.*
  - *The worldwide portable flash player market exploded in 2003 and is expected to grow from 12.5 mln units in 2003 to over 50 mln units in 2008.*
  - *Global 3G subscribers will grow from an estimated 45 mln at the end of 2004 to 85 mln in 2005.*
  - *The number of broadband lines worldwide increased by almost 55% to over 123 mln in the 12 months to the end of June 2004.*
  - *Today's DVR (digital video recorders) users - 5% of households - will grow to 41% within five years.*
  - 79% of all high-end processors are used in embedded systems
  - **The future is embedded, Embedded is the future!**

# Characteristics of Embedded Systems

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Price



Functionality



Performance



Size



Power



Time-to-market



Maintainability

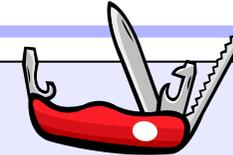


Safety

# Characteristics of Embedded Systems (1)

- Must be **dependable**,

- **Reliability  $R(t)$**  = probability of system working correctly provided that it was working at  $t=0$
- **Maintainability  $M(d)$**  = probability of system working correctly  $d$  time units after error occurred.
- **Availability  $A(t)$** : probability of system working at time  $t$
- **Safety**: no harm to be caused
- **Security**: confidential and authentic communication



Even perfectly designed systems can fail if the assumptions about the workload and possible errors turn out to be wrong. Making the system dependable must not be an after-thought, it must be considered from the very beginning

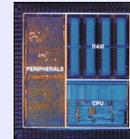
## Characteristics of Embedded Systems (2)

- Must be **efficient**

- Energy efficient



- Code-size efficient  
(especially for systems on a chip)



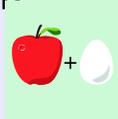
- Run-time efficient



- Weight efficient



- Cost efficient



- **Dedicated** towards a certain **application**

Knowledge about behavior at design time can be used to minimize resources and to maximize robustness

- **Dedicated user interface**

(no mouse, keyboard and screen)

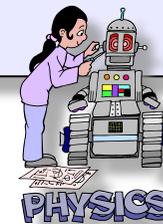


- **Hybrid systems** (analog + digital parts).



## Characteristics of Embedded Systems (3)

- Many ES must meet **real-time constraints**
  - A real-time system must react to stimuli from the controlled object (or the operator) within the time interval **dictated** by the environment.
  - For real-time systems, right answers arriving too late are wrong.
  - „**A real-time constraint is called hard, if not meeting that constraint could result in a catastrophe**“ [Kopetz, 1997].
  - All other time-constraints are called **soft**.
  - A guaranteed system response has to be explained without statistical arguments
- Frequently **connected to physical environment** through sensors and actuators,



## Characteristics of Embedded Systems (4)

- Typically, ES are **reactive systems**:  
„A reactive system is one which is in continual interaction with its environment and executes at a pace determined by that environment“ [Bergé, 1995]  
Behavior depends on input **and current state**.
  - ☞ automata model appropriate,  
model of computable functions inappropriate.

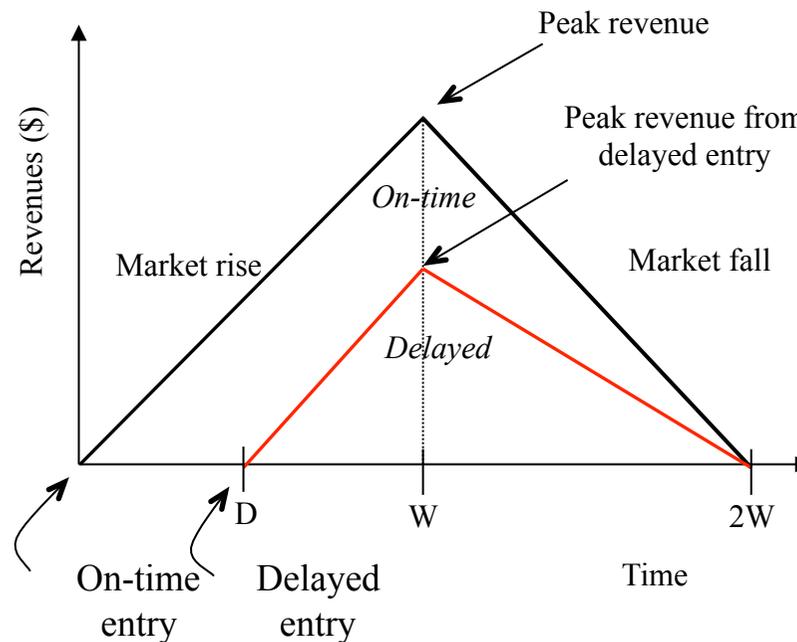


Not every ES has all of the above characteristics.

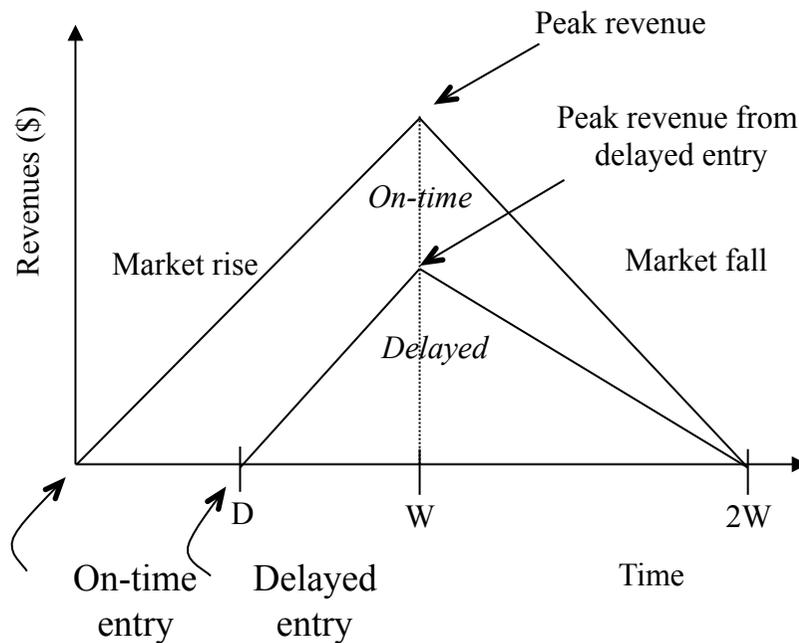
**Def.: Information processing systems having most of the above characteristics are called embedded systems.**

# Time-to-market

- ❑ Often must meet tight deadlines.
  - ✓ 6 month market window is common.
  - ✓ Can't miss back-to-school window for calculator.



# Losses Due to Delayed Market Entry



## Simplified revenue model

Product life =  $2W$ , peak at  $W$

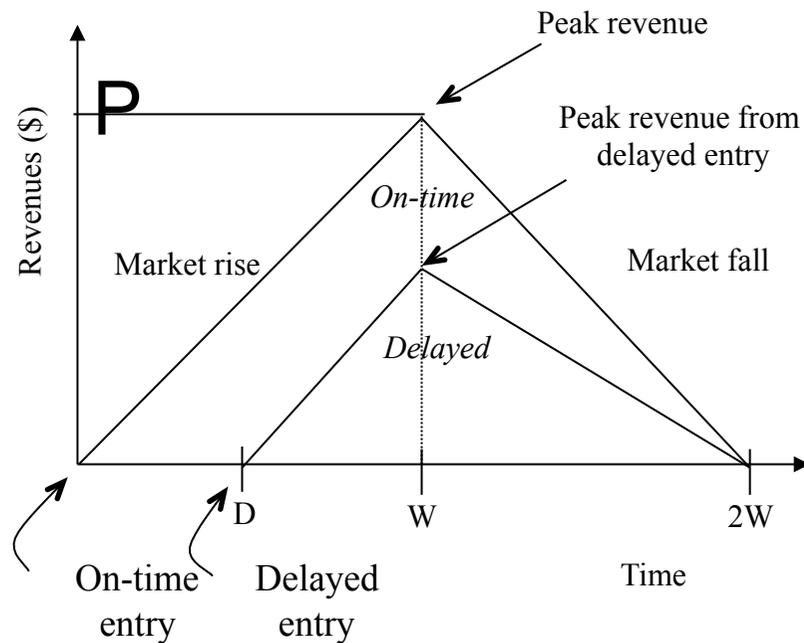
Time of market entry defines a triangle, representing market penetration

Triangle area equals revenue

## Loss

The difference between the on-time and delayed triangle areas

## Losses Due to Delayed Market Entry, cont'd.



Area =  $1/2 * \text{base} * \text{height}$

On-time =  $1/2 * 2W * P$

Delayed =  $1/2 * (W-D+W)*(W-D)*P/W$

Percentage revenue loss =  $(D(3W-D)/2W^2)*100\%$

Try some examples

Lifetime  $2W=52$  wks, delay  $D=4$  wks

$(4*(3*26 - 4)/2*26^2) = 22\%$

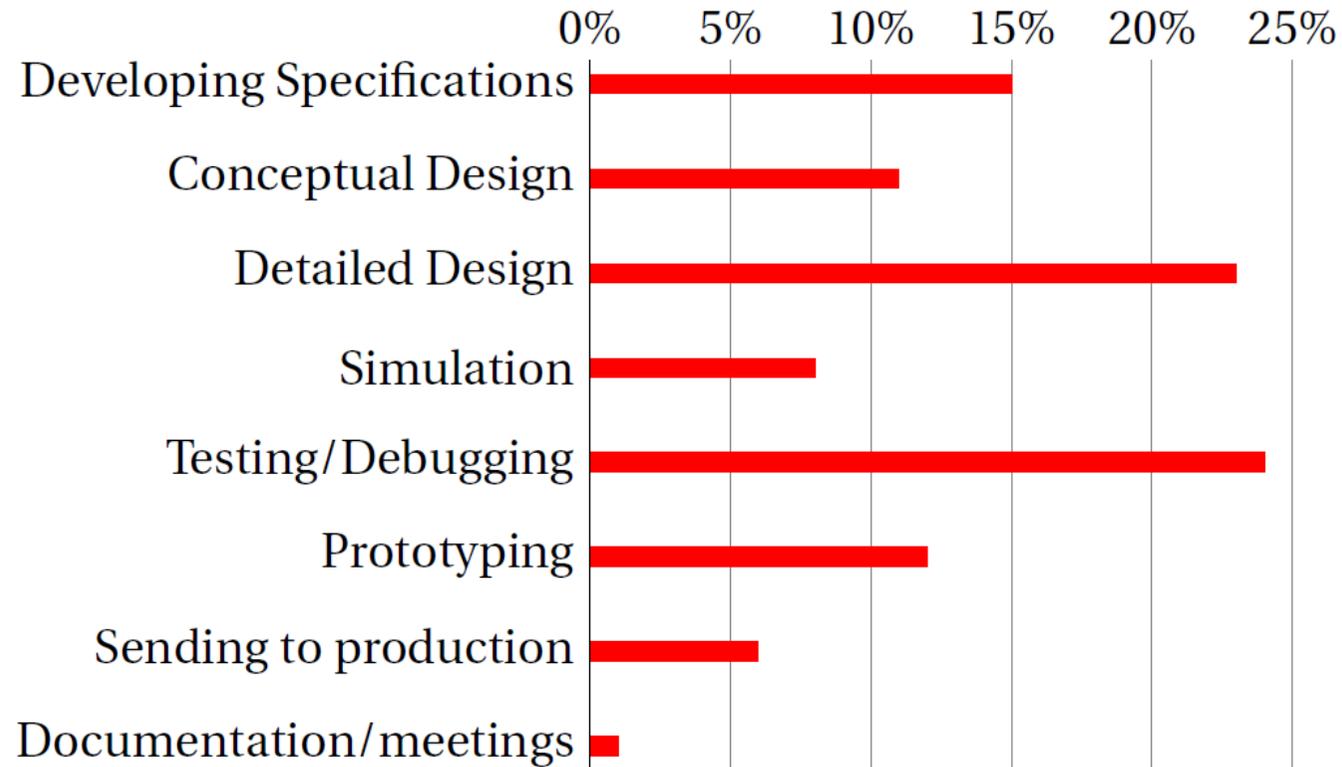
Lifetime  $2W=52$  wks, delay  $D=10$  wks

$(10*(3*26 - 10)/2*26^2) = 50\%$

Delays are costly!

From *Embedded Systems Design: A Unified Hardware/Software Introduction*, (c) 2000 Vahid/Givargis

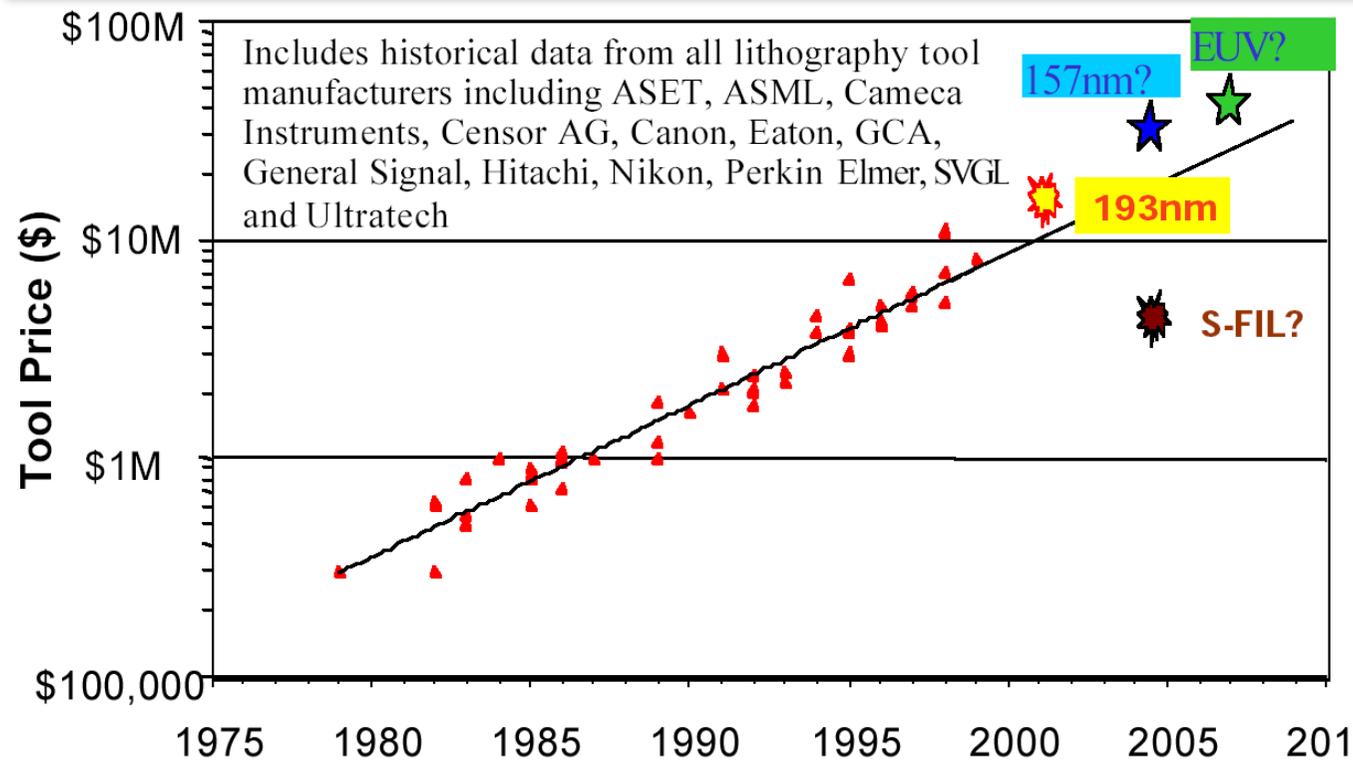
# Development costs



Source: 2009 Embedded Market Study

# Challenges for implementation in hardware

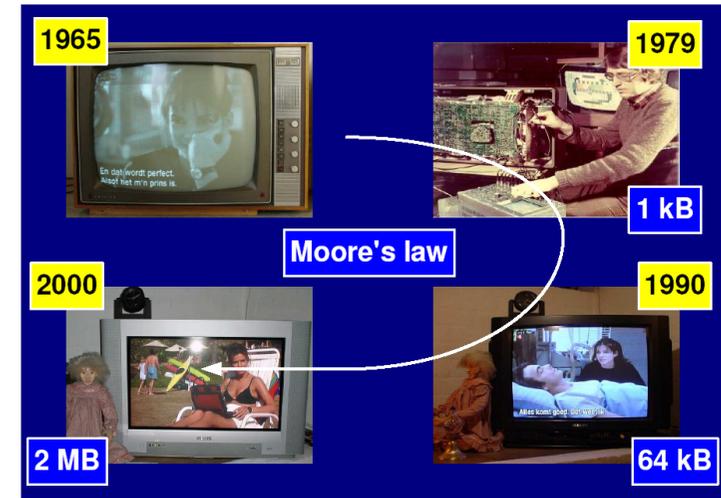
- Lack of flexibility (changing standards).
- Mask cost for specialized HW becomes very expensive



➡ Trend towards implementation in Software

# Software complexity is a challenge

- Exponential increase in software complexity
- In some areas code size is doubling every 9 months [ST Microelectronics, Medea Workshop, Fall 2003]
- ... > 70% of the development cost for complex systems such as automotive electronics and communication systems are due to software development [A. Sangiovanni-Vincentelli, 1999]



Rob van Ommering, COPA Tutorial, as cited by: Gerrit Müller: Opportunities and challenges in embedded systems, Eindhoven Embedded Systems Institute, 2004



# Challenges in embedded system design

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- How much hardware do we need?
  - ✓ How many processors? How big are they? How much memory?
- How do we meet performance requirements?
  - ✓ What's in hardware? What's in software?
  - ✓ Faster hardware or cleverer software?
- How do we minimize power?
  - ✓ Turn off unnecessary logic? Reduce memory accesses?
- How do we ship in time?
  - ✓ Off-the-shelf chips? IP-reuse?

# More challenges for embedded software



- Dynamic environments
- Capture the required behaviour!
- Validate specifications
- Efficient translation of specifications into implementations!
- How can we check that we meet real-time constraints?
- How do we validate embedded real-time software? (large volumes of data, testing may be safety-critical)



## Challenges, etc.

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- Does it really work?
  - ✓ Is the specification correct?
  - ✓ Does the implementation meet the spec?
  - ✓ How do we test for real-time characteristics?
  - ✓ How do we test on real data?
- How do we work on the system?
  - ✓ Observability, controllability?
  - ✓ What is our development platform?
- How do we make our ends meet?
- How do we reduce size/weight?

## Required Designers

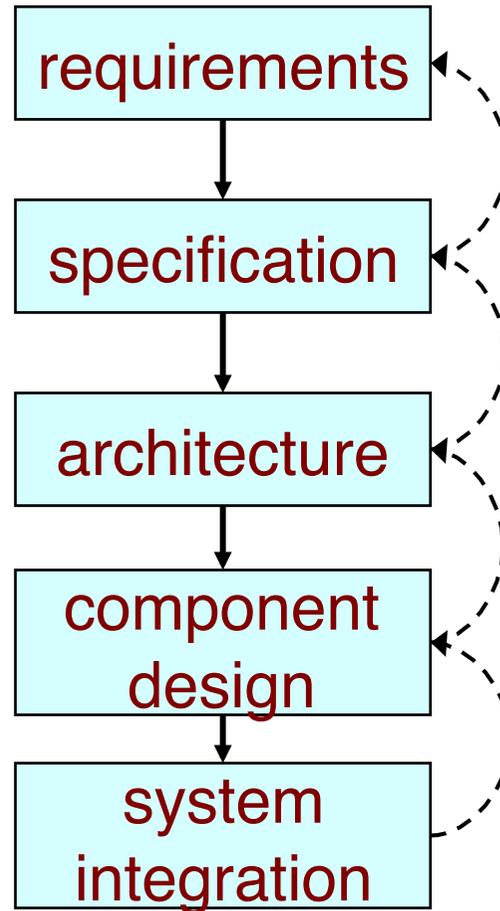
- ❑ Expertise with both **software and hardware** is needed to optimize design metrics
  - ✓ Not just a hardware or software expert
  - ✓ A designer must be comfortable with various technologies in order to choose the best for a given application and constraints
  - ✓ A designer must be able to communicate with teammates of various background

# Design methodologies

- ❑ A procedure for designing a system.
- ❑ Understanding your methodology helps you ensure you didn't skip anything.
- ❑ Compilers, software engineering tools, computer-aided design (CAD) tools, etc., can be used to:
  - ✓ help automate methodology steps;
  - ✓ keep track of the methodology itself.

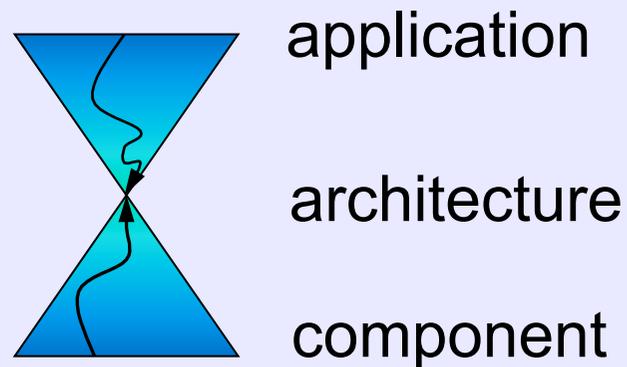
# Levels of abstraction

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## Top-down vs. bottom-up

- ❑ Top-down design:
  - ✓ start from most abstract description;
  - ✓ work to most detailed.
- ❑ Bottom-up design:
  - ✓ work from small components to big system.
- ❑ Real design uses both techniques.



# Requirements

- ❑ Plain language description of what the user wants and expects to get.
- ❑ May be developed in several ways:
  - ✓ talking directly to customers;
  - ✓ talking to marketing representatives;
  - ✓ providing prototypes to users for comment.

# Functional vs. non-functional requirements

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- ❑ Functional requirements:
  - ✓ output as a function of input.
- ❑ Non-functional requirements:
  - ✓ time required to compute output;
  - ✓ size, weight, etc.;
  - ✓ power consumption;
  - ✓ reliability;
  - ✓ etc.

# One requirements form

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name

purpose

inputs

outputs

functions

performance

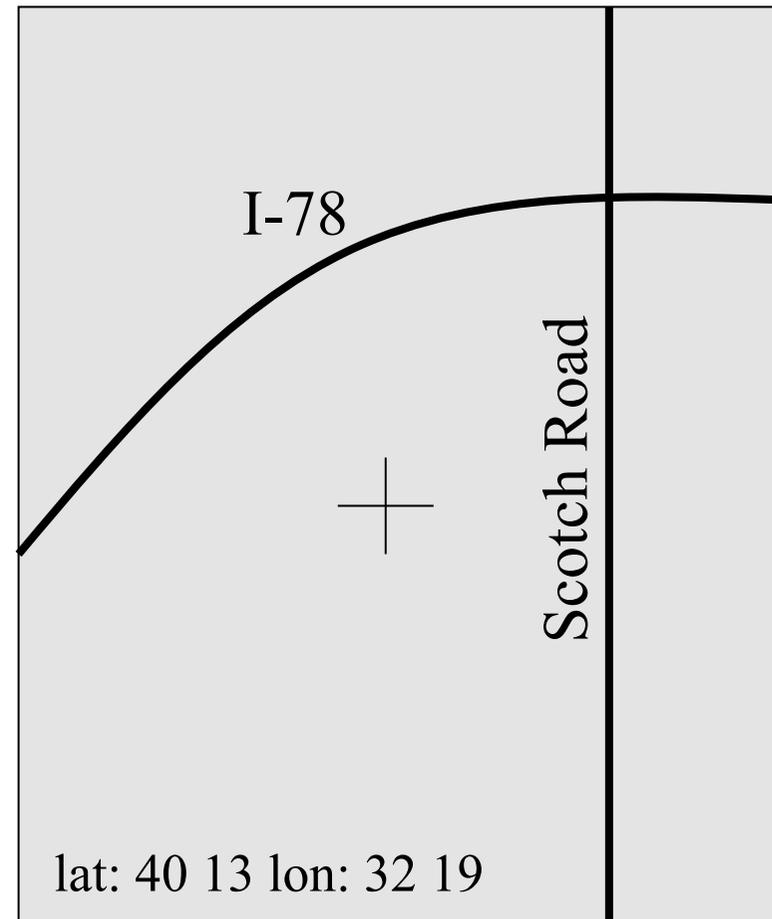
manufacturing cost

power

physical size/weight

# Example: GPS moving map requirements

- ❑ Moving map obtains position from GPS, paints map from local database.



# GPS moving map needs

- ❑ **Functionality:** For automotive use. Show major roads and landmarks.
- ❑ **User interface:** At least 400 x 600 pixel screen. Three buttons max. Pop-up menu.
- ❑ **Performance:** Map should scroll smoothly. No more than 1 sec power-up. Lock onto GPS within 15 seconds.
- ❑ **Cost:** \$500 street price = approx. \$100 cost of goods sold.
- ❑ **Physical size/weight:** Should fit in dashboard.
- ❑ **Power consumption:** 8 hours on 4 AAs

# GPS moving map requirements form

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name	GPS moving map
purpose	consumer-grade moving map for driving
inputs	power button, two control buttons
outputs	back-lit LCD 400 X 600
functions	5-receiver GPS; three resolutions; displays current lat/lon
performance	updates screen within 0.25 sec of movement
manufacturing cost	\$100 cost-of-goods-sold
power	100 mW
physical size/weight	no more than 2: X 6:, 12 oz.



# Specification

- ❑ A more precise description of the system:
  - ✓ should not imply a particular architecture;
  - ✓ provides input to the architecture design process.
- ❑ May include functional and non-functional elements.
- ❑ May be executable or may be in mathematical form for proofs.

# GPS specification

## □ Should include:

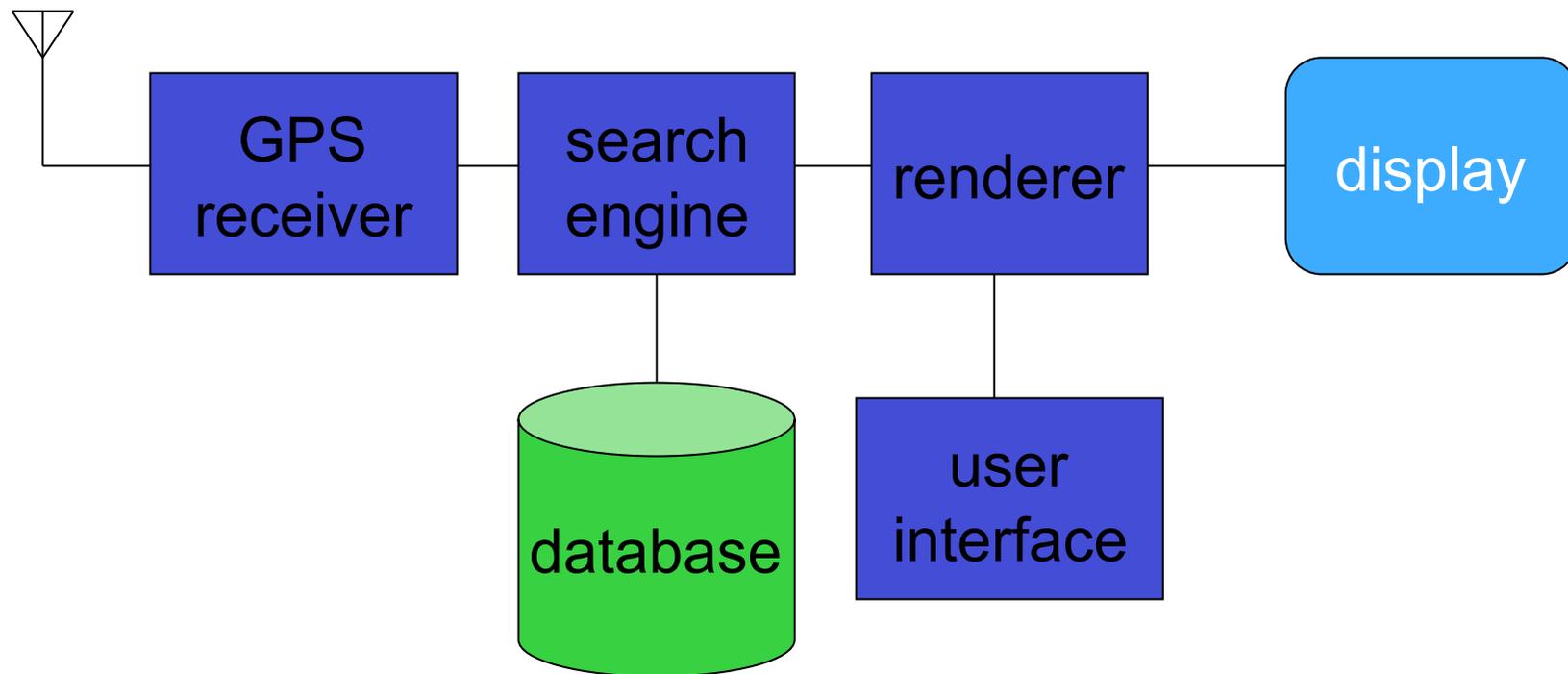
- ✓ What is received from GPS;
- ✓ map data;
- ✓ user interface;
- ✓ operations required to satisfy user requests;
- ✓ background operations needed to keep the system running.

# Architecture design

- ❑ What major components go satisfying the specification?
- ❑ Hardware components:
  - ✓ CPUs, peripherals, etc.
- ❑ Software components:
  - ✓ major programs and their operations.
- ❑ Must take into account functional and non-functional specifications.

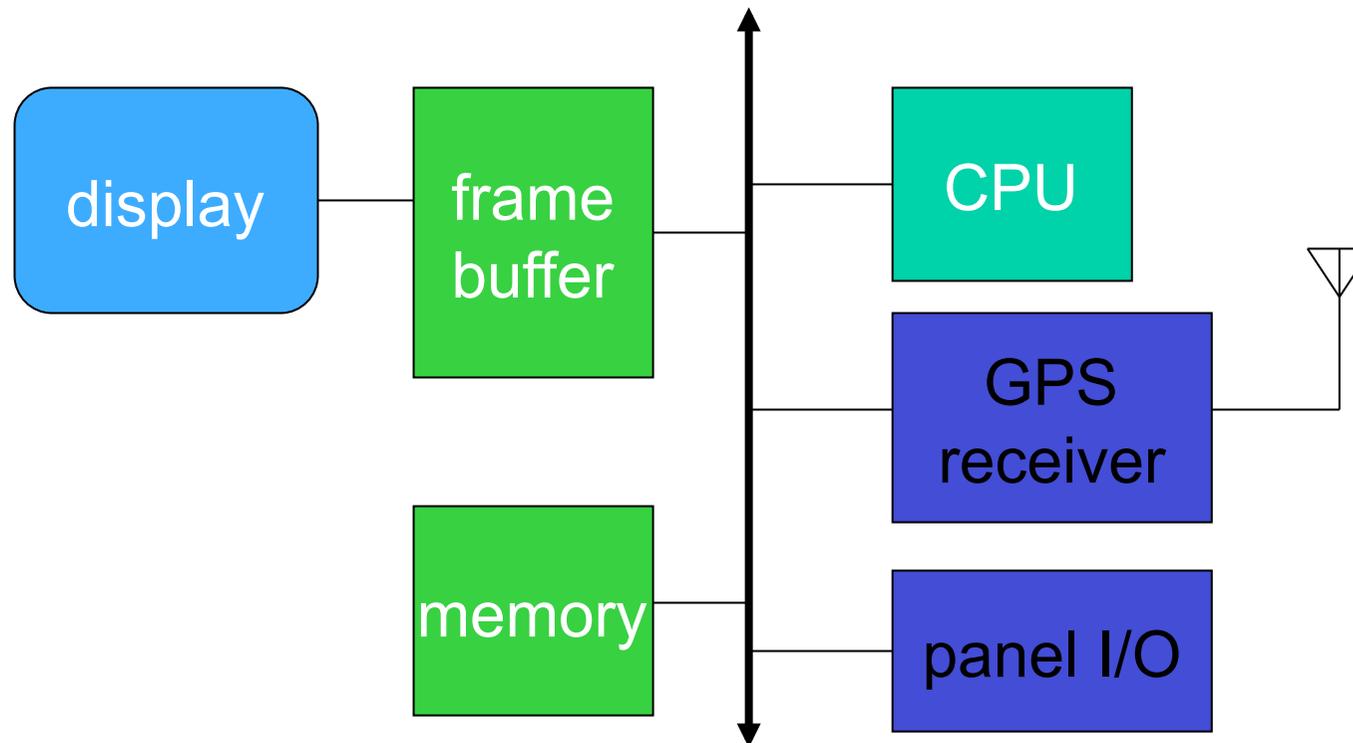
# GPS moving map block diagram

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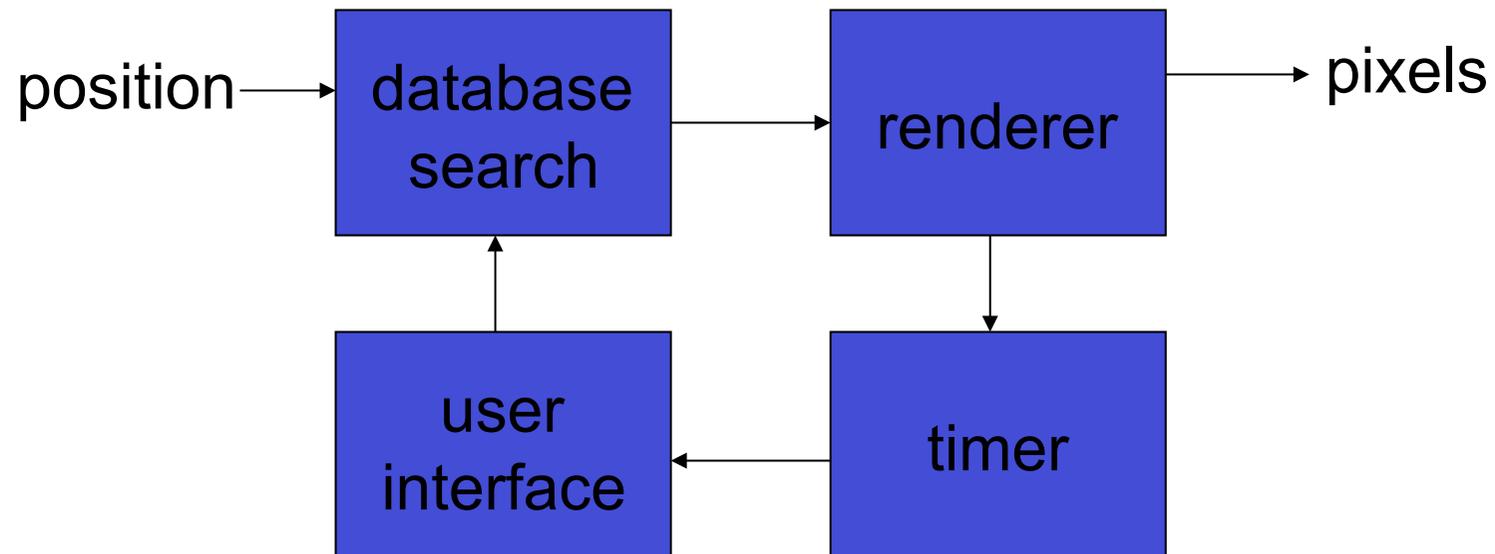
# GPS moving map hardware architecture

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# GPS moving map software architecture

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# Designing hardware and software components

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- Must spend time architecting the system before you start coding.
- Some components are ready-made, some can be modified from existing designs, others must be designed from scratch.

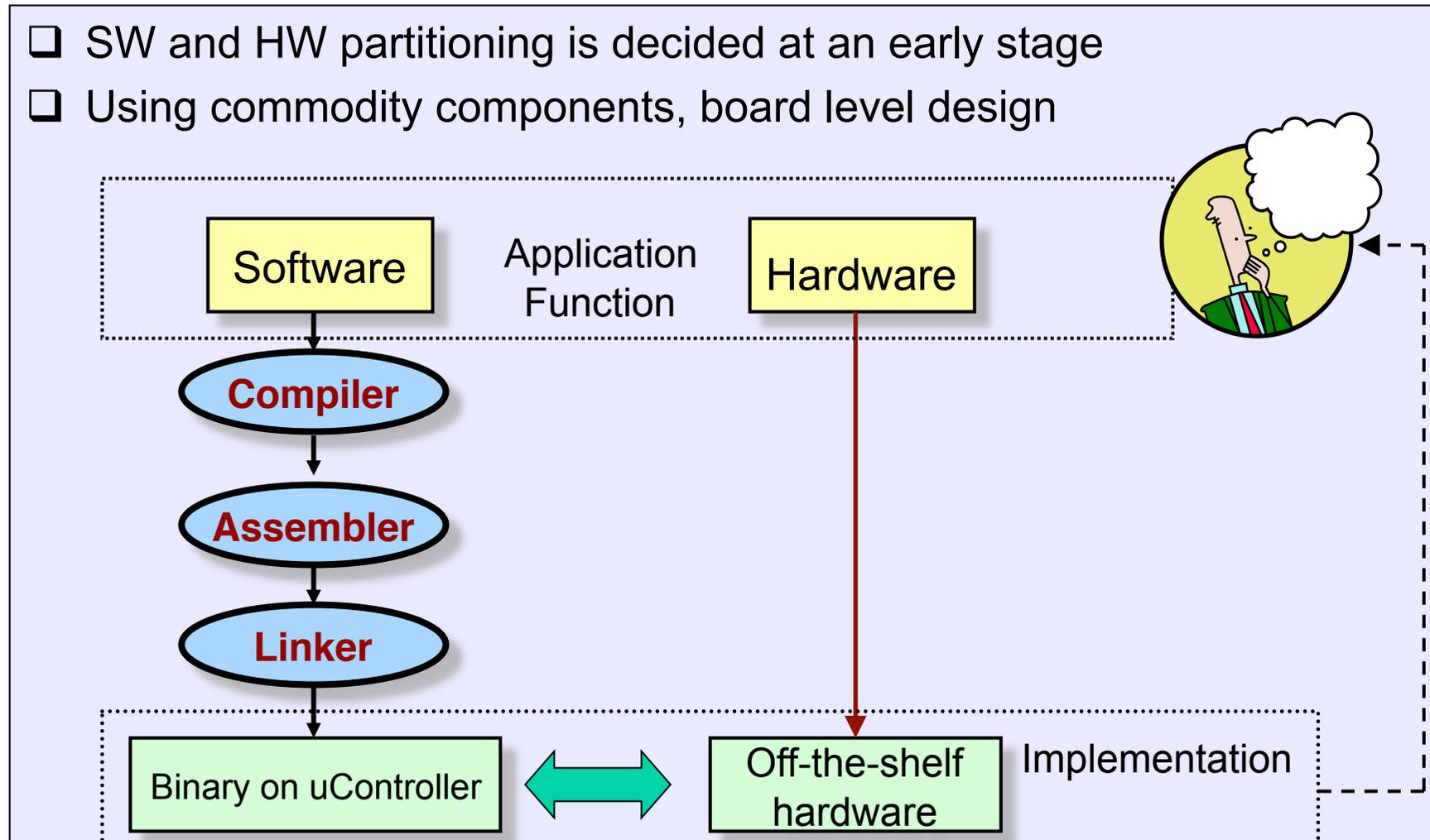
# System integration

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- Put together the components.
  - ✓ Many bugs appear only at this stage.
- Have a plan for integrating components to uncover bugs quickly, test as much functionality as early as possible.

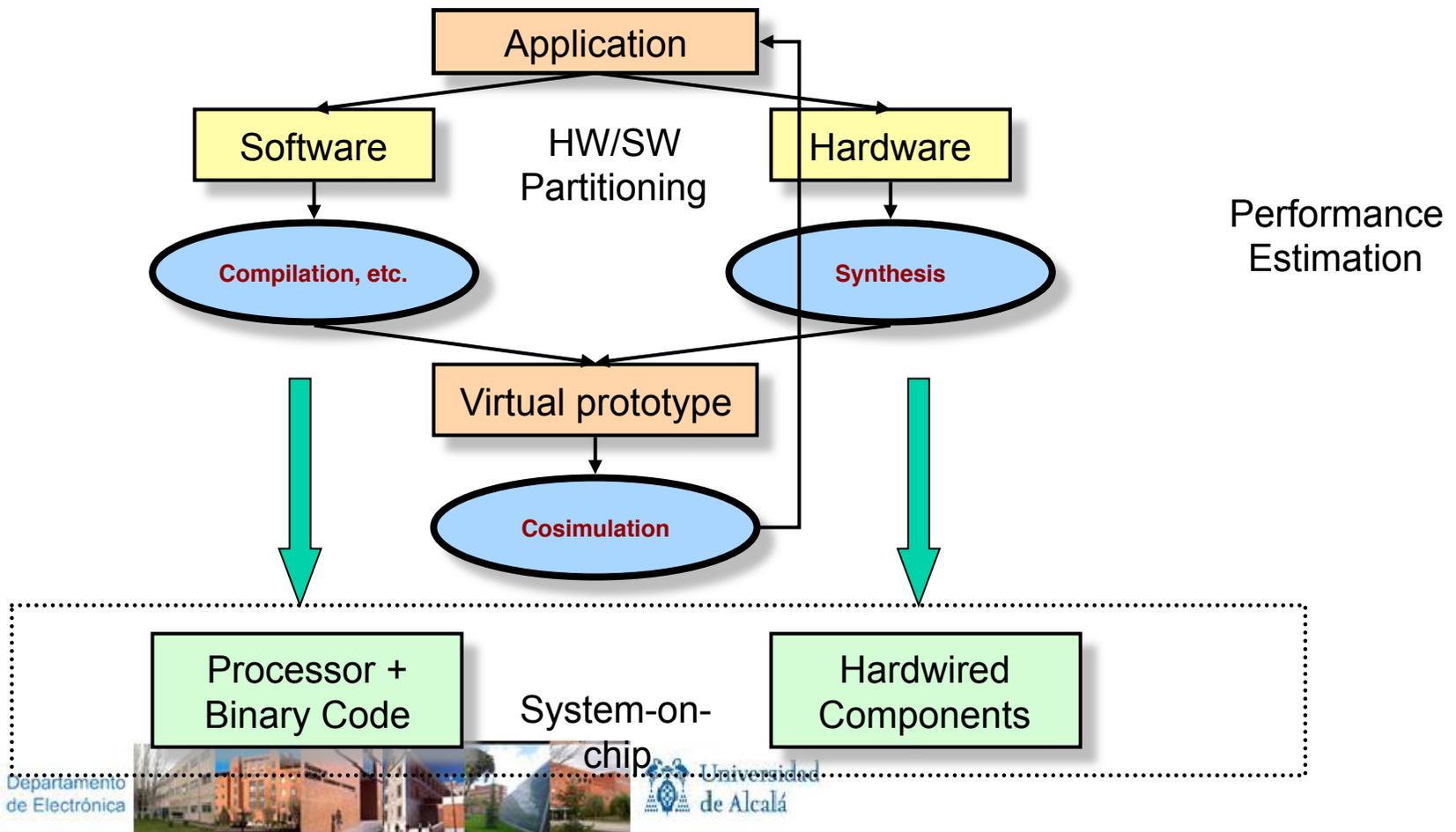
# Traditional Embedded System Design

- ❑ SW and HW partitioning is decided at an early stage
- ❑ Using commodity components, board level design



# HW/SW Codesign Style

- ❑ An integrated design flow of hardware and software
- ❑ Often targeting SoCs, not constrained by commodity components



# Summary

- ❑ Embedded computers are all around us.
  - ✓ Many systems have complex embedded hardware and software.
- ❑ Embedded systems pose many design challenges: design time, deadlines, power, etc.
- ❑ Design methodologies help us manage the design process.